

Molecular Fragment Mining for Drug Discovery

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Abstract. The main task of drug discovery is to find novel bioactive molecules, i.e., chemical compounds that, for example, protect human cells against a virus. One way to support solving this task is to analyze a database of known and tested molecules in order to find structural properties of molecules that determine whether a molecule will be active or inactive, so that future chemical tests can be focused on the most promising candidates. A promising approach to this task was presented in [2]: an algorithm for finding molecular fragments that discriminate between active and inactive molecules. In this paper we review this approach as well as two extensions: a special treatment of rings and a method to find fragments with wildcards based on chemical expert knowledge.

1 Introduction

The computer-aided analysis of molecular databases plays an increasingly important role in drug discovery. One of its major goals is to find structural properties of molecules that determine whether a molecule is active or inactive, for example, w.r.t. the protection of human cells against a virus. Knowledge about such properties can then be used to focus the expensive and time-consuming real chemical tests on the most promising candidate compounds.

The approach to this task we are considering here is based on finding a set of *discriminative fragments*. Such fragments are parts of molecules that are frequent in the set of active molecules and rare in the set of inactive ones and thus discriminate between the two classes. The rationale is that discriminative fragments may be the key substructures that determine the activity of compounds and therefore can be used to predict the activity of molecules.

Several algorithms have been suggested for finding discriminative fragments efficiently. [4] presented an approach that finds linear fragments using a method that is based on the well-known Apriori algorithm for association rule mining [1].

However, the restriction to chains of atoms is limiting in many real-world applications, since substructures of interest often contain rings or branching points. The approach presented in [2] does not suffer from this restriction. It is based on a transfer of the Eclat algorithm for association rule mining [8] and thus avoids the expensive reembedding of fragments. Another approach that can find arbitrary fragments was proposed in [5]. The main differences between these approaches are the ways in which fragments of interest are generated, an issue we consider in more detail when we study the algorithm of [2] below.

In this paper we also review two extensions of the algorithm suggested in [2]. Due to a symmetry problem that makes it impossible to suppress all redundant search, this algorithm runs into problems if fragments contain a lot of rings. The first extension solves this problem by finding rings in a preprocessing step and then treating them as units in the mining algorithm, thus making the search much more efficient [3]. The second extension is inspired by the fact that certain atom types can sometimes be considered as equivalent from a chemical point of view. To handle such cases, we introduce wildcard atoms into the search [3].

As a test case for our extended algorithm we use a publicly available database of the National Cancer Institute, namely the NCI-HIV database (DTP AIDS Antiviral Screen) [7], which was also used in [2] and [4]. This database is the result of an effort to discover new compounds capable of inhibiting the HI virus (HIV). The screen utilized a soluble formazan assay to measure protection of human CEM cells from HIV-1. Compounds able to provide at least 50% protection to CEM cells were retested. Compounds providing at least 50% protection on retest were listed as moderately active (*CM*). Compounds that reproducibly provided 100% protection were listed as confirmed active (*CA*). Compounds not meeting these criteria were listed as confirmed inactive (*CI*). The dataset consists of 41,316 compounds, of which we have used 37,171. For the remaining 4,145 no structural information was available at the time the experiments reported here were carried out. Each compound has a unique identification number (NSC number), by which we refer to it. Out of the 37,171 compounds we used, 325 belong to class *CA*, 896 to class *CM*, and the remaining 35,950 to class *CI*. We neglected the 896 moderately active compounds in our experiments. The size of this database stresses the need for a truly efficient and scalable algorithm. The method described in [2], for example, could only be applied to this data set by using small initial fragments as "seeds" for the underlying search algorithm.

For some other experiments we used the NCI-H23 database (DTP Human Tumor Cell Line Screen) [9] of the National Cancer Institute's Development Therapeutics Program, which has a similar purpose as the NCI-HIV database and which is also publicly available. This database lists 35,985 compounds, which have been tested for evidence of the ability to inhibit the growth of human tumor cell lines. The compounds were tested at five different concentrations and w.r.t. sixty different human tumor cell lines. We used the results for a specific type of lung cancer. In these results 5,996 compounds are classified as active based on the concentration parameter GI50 being greater than 5 (see [9] for more details). With our algorithm we tried to find discriminative fragments that separate these active compounds from the rest.

2 Molecular Fragment Mining

As stated above, the goal of molecular fragment mining is to find discriminative fragments in a database of molecules, which are classified as either active or inactive. To achieve this goal, the algorithm presented in [2] represents molecules as attributed graphs and carries out a depth first search on a tree of fragments. Going down one level in this search tree means extending a fragment by adding a bond and maybe an atom to it. For each fragment a list of embeddings into the available molecules is maintained, from which the lists of embeddings of its extensions can easily be constructed. As a consequence, expensive reembeddings of fragments are not necessary. The support of a fragment, that is, the number of molecules it is contained in, is then determined by simply counting the number of different molecules the embeddings refer to. (Note that there may be more than one embedding of a fragment into the same molecule.) If the support of a fragment is high in the set of active molecules and low in the set of inactive molecules it is reported as a discriminative fragment.

The most important ingredients of the algorithm are different search tree pruning methods, which can be grouped into three categories: *size based pruning* (which restricts the size of fragments), *support based pruning* (which discards too infrequent fragments), and *structural pruning*. Among these the latter is the most important and most complicated. It is based on a set of rules that defines a local order of the extensions of a fragment, which is used to avoid redundant searches, that is, multiple construction and test of the same fragment.

The main idea is that two extensions, if both are applied (one after the other) to the same fragment, lead to the same extended fragment, regardless of which of them is applied first. Thus, without restrictions, the same fragments would be considered in several branches of the search tree, because there are several ways of building the same fragment by adding bonds and atoms to a core fragment (which may be a single atom). To avoid this redundancy, the extensions are ordered, and once an extension is carried out, any extension preceding it in this order is prohibited. The order is defined locally, because it depends on the structure of the fragment to be extended. Ideally, ordering the extensions should lead to a situation in which there is exactly one way of constructing each possible fragment, so that there is a unique path in the search tree leading to it.

To be more specific, the algorithm works as follows: The atoms of the fragments that are constructed are numbered in the order in which they have been added to the fragment. Whenever an embedding is extended, the number of the atom, from which the added bond started, is recorded in the resulting extension. When the extended embedding is to be extended itself, only bonds are considered that start from atoms having numbers no less than this recorded number. That is, only the atom extended in the preceding step and atoms added later than this atom can be the starting point of a new bond. With this simple scheme it is immediately avoided that two bonds, call them A and B , which start from different atoms, are added in the order A, B in one branch of the search tree and in the order B, A in another. Since either the atom A starts from or the atom B starts from must have a smaller number, one of the orders is ruled out.

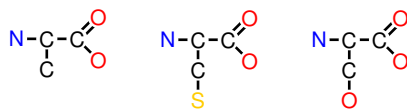


Fig. 1. The amino acids glycine, cysteine and serine.

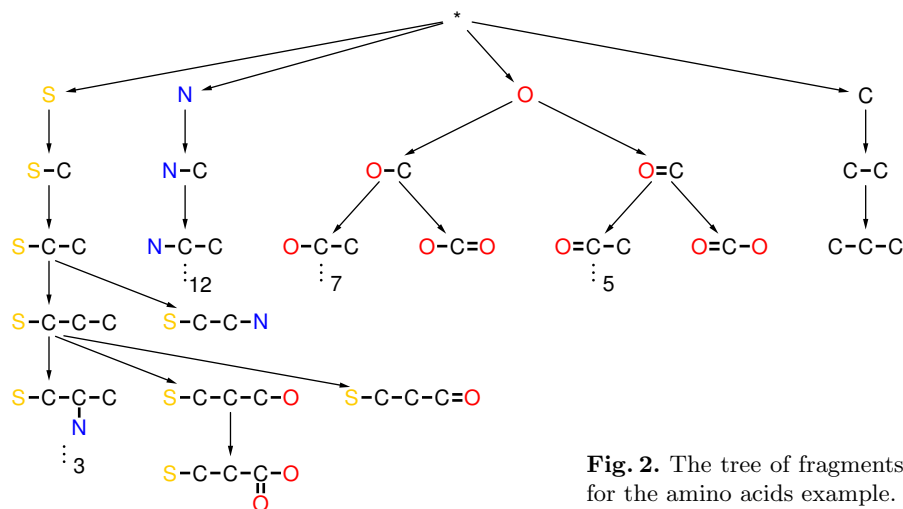
However, two or more bonds may start from the same atom. Therefore it is also necessary to define an order on bonds, to avoid that two different bonds A and B that start from the same atom are added in the order A, B in one branch of the search tree and in the order B, A in another. This order on bonds is, of course, arbitrary. Most naturally, however, single bonds precede aromatic bonds, which precede double bonds, which precede triple bonds. Finally, within extensions by bonds of the same type starting from the same atom, the order is determined by (1) whether the atom the bond leads to is already in the fragment or not and (2) the type of this atom. To take care of the bond type etc., it is recorded in each embedding which bond was added last.

Ideally, extensions would be totally ordered by these rules. However, this is not the case. There are situations in which two bonds of the same type start from the same atom and lead to atoms of the same type. In such cases the locally available information is not sufficient to define an order of the extensions. However, it is also not possible to simply process these extensions in an arbitrary order, as an example in [2] demonstrates. As a consequence, they have to be considered in every possible order, which can lead to considerable redundant search. This is the main reason for the first extension of this algorithm (see below).

Since the search tree we traverse in the modified algorithm differs slightly from the one used in [2], we illustrate it with a simple example. Figure 1 shows the amino acids glycine, cysteine and serine with hydrogens and charges neglected. The upper part of the tree (or forest if the empty fragment at the root is removed) that is traversed by the algorithm for these molecules is shown in Figure 2. The first level contains individual atoms, the second connected pairs and so on. The dots indicate subtrees that are not depicted in order to keep the figure understandable. The numbers next to these dots state the number of fragments in these subtrees, giving an indication of the total size of the tree.

The order, in which the atoms on the first level of the tree are processed, is determined by their frequency of occurrence in the molecules. The least frequent atom type is considered first. Therefore the algorithm starts on the left by embedding a sulfur atom into the example molecules. That is, the molecules are searched for sulfur atoms and their locations are recorded. In our example there is only one sulfur atom in cysteine, which leads to one embedding of this (one atom) fragment. This fragment is then extended (depth first search) by a single bond and a carbon atom ($-C$), which produces the fragment $S-C$ on the next level. All other extensions of fragments that are generated by going down one level in the tree are created in an analogous way.

If a fragment allows for more than one extension (as is the case, for instance, for the fragments $O-C$ and $S-C-C-C$), we sort them according to the local ordering rules listed above. As explained a few paragraphs up, the main purpose of this



local order is to prevent certain extensions to be generated in certain branches of the search tree, in order to avoid redundant searches. For instance, the fragment S-C-C-C-O is not extended by adding a single bond to a nitrogen atom at the second carbon atom, because this extension has already been considered in the subtree rooted at the left sibling of this fragment.

Furthermore, in the subtree rooted at the nitrogen atom, extensions by a bond to a sulfur atom are ruled out, since all fragments containing a sulfur atom have already been considered in the tree rooted at the sulfur atom. Similarly, neither sulfur nor nitrogen are considered in the tree rooted at the oxygen atom, and the rightmost tree contains fragments that consist of carbon atoms only.

Although the example molecules considered here do not contain any rings, it is clear that we have to handle them in the general case. While the original algorithm treated extensions to new atoms and extensions closing rings basically alike, only handling them through an ordering rule to avoid redundant search (see above), the new algorithm processes them in two separate phases: Even though extensions closing rings are allowed in any step, once a ring has been closed in a fragment, the possible future extensions are restricted to closing rings as well. While this does not lead to performance improvements, it has certain advantages w.r.t. the order in which fragments are generated.

Up to now we described how the search tree is organized, i.e., the manner in which the candidates for discriminative fragments are generated and the order in which they are considered. However, in an application this search tree is not traversed completely—that would be much too expensive for a real-world database. Since a discriminative fragment must be frequent in the active molecules and extending a fragment can only reduce the support (because only fewer molecules can contain it), subtrees can be pruned as soon as the support falls below a user-defined threshold (support based pruning). Furthermore, the depth of the tree may be restricted, thus limiting the size of the fragments (size based pruning).

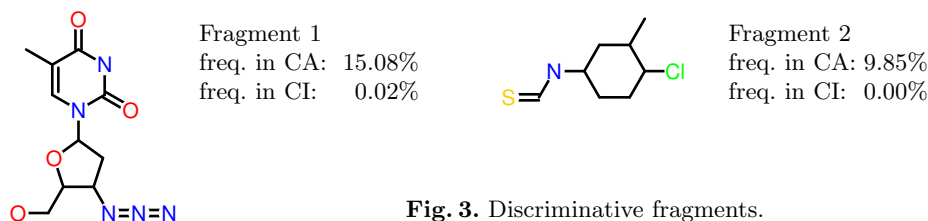


Fig. 3. Discriminative fragments.

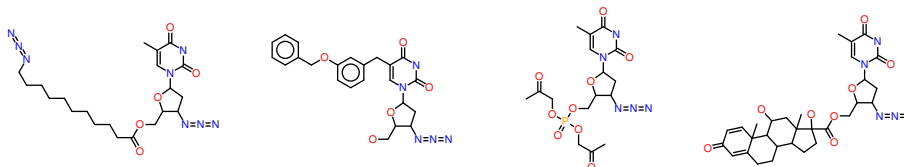


Fig. 4. Example molecules containing Fragment 1.

Discriminative fragments should also be rare in the inactive molecules, defined formally by an user-specified upper support threshold. However, this upper threshold cannot be used to prune the search tree: Even if a fragment does not satisfy this threshold, its extension may (again extending a fragment can only reduce the support), and thus it has to be generated. Therefore this threshold is only used to filter the fragments that are frequent in the active molecules. Only those fragments that satisfy this threshold (in addition to the minimum support threshold in the active molecules) are reported as discriminative fragments.

In [2] the original form of this algorithm was applied to the NCI-HIV database with considerable success. Several discriminative fragments were found, some of which could be related to known classes of HIV inhibitors. Among the results are, for example, the two fragments shown in Figure 3. Fragment 1 is known as AZT, a well-known nucleoside reverse transcriptase inhibitor, which was the first drug approved for anti-HIV treatment. AZT is covered by 49 of the 325 (15.08%) compounds in *CA* and by only 8 of the 35,950 (0.02%) compounds in *CI*. Four examples of compounds in the NCI-HIV dataset that are covered by Fragment 1 are shown in Figure 4. Fragment 2 is remarkable, because it is not covered by any compound of the 35,950 inactive ones, but is covered by 31 molecules in *CA* (9.85%). (Fragment 2 was not reported in [2], but in [3]).

3 Rings

An unpleasant problem of the search algorithm as we presented it up to now is that the local ordering rules for suppressing redundant searches are not complete. Two extensions by identical bonds leading to identical atoms cannot be ordered based on locally available information alone. As mentioned, a simple example demonstrating this problem and the reasons underlying it can be found in [2].

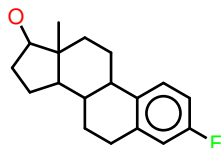


Fig. 5. Example of a steroid, which can lead to problems due to the large number of rings.

As a consequence, a certain amount of redundant search has to be accepted in this case, because otherwise incorrect support values would be computed and it could no longer be guaranteed that all discriminative fragments are found.

Unfortunately, the situation leading to these redundant searches occurs almost always in molecules with rings, whenever the fragment extension process enters a ring. Consequently, molecules with a lot of rings, like the steroid shown in Figure 5—despite all clever search tree pruning—still lead to a prohibitively high search complexity: The original algorithm considers more than 300,000 fragments for the steroid, a large part of which are redundant.

To cope with this problem, a preprocessing step is added to the algorithm, in which rings of the molecules are found and marked. This is done by a simple depth first search that is restricted in depth to the maximum size of rings that are to be found. Usually it suffices to find rings with five and six atoms, because these are most interesting to chemists. In the search process itself, whenever an extension adds a ring bond to a fragment, not only this bond, but the whole ring is added (all bonds and atoms of the ring are added in one step). As a consequence, the depth of the search tree is reduced (from five or six levels to construct a ring to one) and much of redundant search of the basic algorithm is avoided, which leads to enormous speed-ups. For example, the number of fragments generated for the steroid shown in Figure 5 reduces to 93.

On the NCI-HIV database our implementation of the basic algorithm generates 407,364 fragments in *CA* that have a support higher than 15%, for which it needs 45 minutes.⁴ Using ring extensions reduces the number of fragments to 456 which are generated in 13 seconds. Another illustration of the gains resulting from one step ring extensions is provided by the diagrams shown in Figure 6. They display the number of nodes per level in the search tree for the two versions of the algorithm. As can be seen in the left diagram, the search tree of the basic algorithm has a width of approximately 80,000 fragments and a depth of 22 levels. In contrast to this, the width of the search tree using one step ring extensions is approximately 80 fragments, almost a factor of 1000 less.

Furthermore, the shapes of the search trees are remarkable. While with the basic algorithm the tree width grows roughly exponentially with the depth of the tree, until a maximum is reached, with the ring extension algorithm the tree width grows only roughly linearly with the depth. As a side note, these diagrams also justify the use of a depth first search in our algorithm: The typical and extremely high width to depth ratio of the tree makes a breadth first search disadvantageous or, for the basic algorithm, infeasible.

⁴ Our experiments were run using a Java implementation on a 1GHz Xeon Dual-Processor machine with 1GB of main memory using jre1.4.0

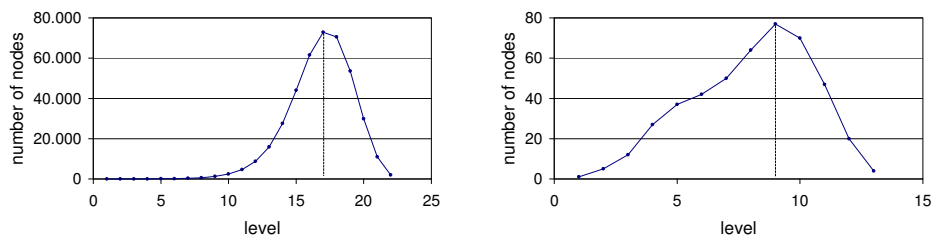


Fig. 6. Number of nodes per level for the algorithms with and without ring extensions.

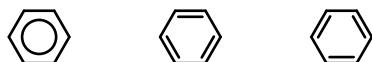


Fig. 7. Aromatic and Kekulé representations of benzene.

Besides a considerable reduction of the running time, treating rings as units when extending fragments has other advantages as well. In the first place, it makes a special treatment of atoms and bonds in rings possible, which is especially important for aromatic rings. For example, benzene can be represented in different ways as shown in Figure 7. On the left, all six bonds are represented as aromatic bonds, while the other two representations—called *Kekulé structures*—use alternating single and double bonds. A chemist, however, considers all three representations as equivalent. With the basic algorithm this is not possible, because it would require treating single, double, and aromatic bonds alike, which obviously leads to undesired side effects. By treating rings as units, however, these special types of rings can be identified in the preprocessing step and then be transformed into a standard aromatic ring.

Secondly, one step ring extensions make the support values associated with a fragment more easily interpretable. To see this, consider the two fragments shown in Figure 8. The left was found with the basic algorithm, the right with the ring extension algorithm. At first glance it may be surprising that the two fragments look alike, but are associated with different support values (74 compounds, or 22.77%, for the basic algorithm and 65 compounds, or 20.00%, for the ring extension algorithm). However, the reason for this is very simple. While with the basic algorithm the N-C-C chain extending from the aromatic ring may be a real chain or may be a part of another ring, it must be a real chain with the ring extension algorithm.

The reason is that with the latter it is not possible to walk into a ring bond by bond, because rings are always added in one step. Therefore the ring extension algorithm does not find this fragment, for instance, in the two compounds shown in Figure 9. Although it may appear as a disadvantage at first sight, this behavior is actually highly desirable by chemists and biologists, because atoms in rings and atoms in chains are considered to be different and thus should not be matched by the same fragment. A fragment should either contain a ring or not, but not parts of it, especially if that part can be confused with a chain.



Fig. 8. Frequencies in *CA* with and without ring extensions.

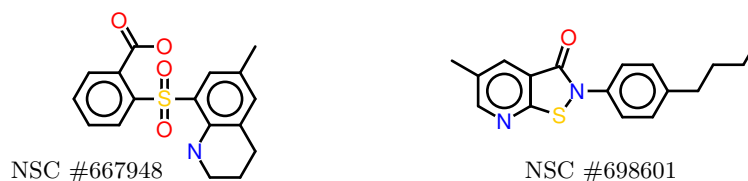


Fig. 9. Compounds that contain Fragment 3 but not Fragment 4.

4 Fragments with Wildcards

Chemists and biologists often regard fragments as equivalent, even though they are not identical. Acceptable differences are, for instance, that an aromatic ring consists only of carbon atoms in one molecule, while in another ring one carbon atom is replaced by a nitrogen atom. An example of such a situation from the NCI-HIV database is shown in Figure 10. A chemist would say that the two molecules shown on the left have basically the same structure and that the difference consists only in the oxygen atom attached to the selenium atom. Therefore they can be treated alike. However, the original algorithm will not find an appropriate fragment because of this mismatch in atom-type [2].

More generally, under certain conditions certain types of atoms can be considered as equivalent from a chemical point of view. To model this equivalence we introduce wildcard atoms into the search, which can match atoms from a user-specified range of atom types. As input we need chemical expert knowledge to define equivalence classes of atoms, possibly conditioned on whether the atom is part of a ring or not (that is, certain atom types may be considered as equiva-

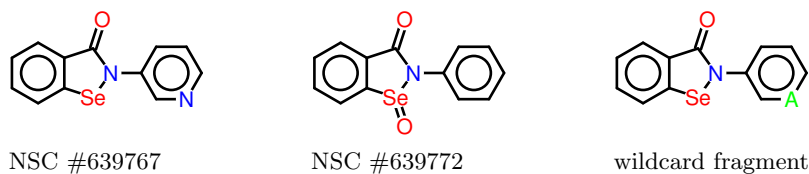


Fig. 10. Matching molecules with a fragment with a wildcard atom.

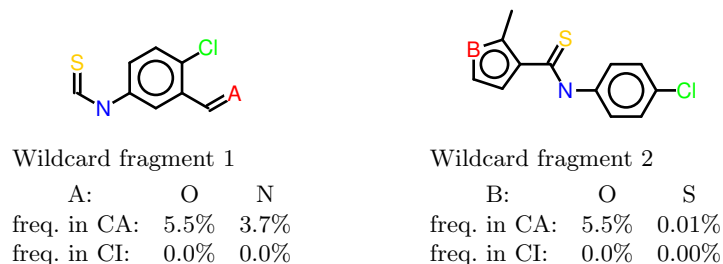


Fig. 11. Fragments with wildcards in the NCI-HIV database.

lent in a ring, but as different in a chain). In the example shown in Figure 10 we may introduce a wildcard atom into the search that can match carbon as well as nitrogen atoms in rings. This enables us to find the fragment on the right, where the green A denotes the wildcard atom.

Formally, wildcard atoms can be introduced into the search process by adding to each node a branch for each group of equivalent atoms, provided that there are at least two molecules that contain different atoms from the group at the position of the wildcard atom. In the later search process, this branch has to be treated in a special way, because it can be pruned if—due to further extensions—the molecules matching the fragment all contain the same atom for the wildcard atom. In our implementation we restrict the number of wildcard atoms in a fragment to a user-defined maximum number.

We applied the wildcard atom approach to the NCI-HIV database, restricting the number of wildcard atoms to one. With this approach the two wildcard fragments shown in Figure 11 are found (among others). The left fragment has a wildcard atom indicated by a red A on the right, which may be replaced by either an oxygen or a nitrogen atom. The (non-wildcard) fragment that results if A is replaced with an oxygen atom has a support of 5.5% in the active compounds, whereas it does not occur in the inactive ones. The fragment with A replaced with nitrogen has a support of 3.7% in the active compounds, and also does not occur in the inactive ones. Consequently, the wildcard fragment has a support of 9.2% in the active compounds. This demonstrates one of the advantages of wildcard fragments, that is, they can be found with much higher minimum support thresholds, which can cut down the output of irrelevant fragments.

However, wildcard fragments can also make it possible to find certain interesting fragments in the first place. This is demonstrated with the wildcard fragment shown in the right in Figure 11. It contains a wildcard atom denoted by a red B in the five-membered aromatic ring on the left, which may be replaced by either an oxygen or a sulfur atom. The interesting point is that the (non-wildcard) fragment that results from replacing B with sulfur has a very low support of 0.01% in the active molecules. This (non-wildcard) fragment would not be found without wildcard atoms, because it is not possible to run the search with a sufficiently low minimum support threshold.

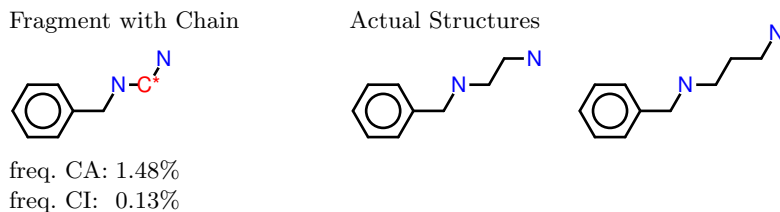


Fig. 12. Example of a carbon chain of varying length from the NCI cancer dataset.

An alternative type of “fuzzy” matches of a fragment to a molecule is concerned with chains of carbon atoms [6]. Often the exact length of a carbon chain in a molecule is not important, as long as it is within a certain range. In this case, the fragment contains an indication of a chain, which may match a certain number of chained carbon atoms in a molecule, where the number may differ for different molecules. This type of fuzzy match can be handled in a similar way as the ring extension we suggested in the previous section: Instead of bond by bond, a carbon chain is added in one step, allowing for different lengths (different number of carbon atoms). An example of a result that can be obtained in this way on the NCI cancer dataset is shown in Figure 12.

5 Conclusions

This paper reviewed some limitations of the molecular fragment mining algorithm introduced in [2] as well as approaches to overcome them. The first extension of the original algorithm deals with the frequent occurrence of rings and their effect on the width of the generated search tree [3]. By preprocessing the molecular database we can identify rings before the actual search starts and then treat them as one entity during the search. This not only speeds up the computation tremendously, but also finds chemically more meaningful fragments since chemists tend to think of rings as one molecular unit. The second extension addresses the need to find fragments that behave chemically similar but are different from a graph point of view. We have proposed a mechanism that allows the user to specify equivalence classes of atoms. Fragments can then contain a certain maximum number of such *wildcard* atoms [3]. Using this method we not only find chemically meaningful fragments, but we can also detect fragments that would otherwise fall below the support threshold. Finally, the search method can be extended to find carbon chains of varying length [6].

The extensions presented here make the original algorithm described in [2] directly applicable to much larger databases and allow the chemist to introduce expert knowledge about similarities on an atomic level, as demonstrated on the NCI-HIV dataset. As a result, the method presented here has been used very successfully, among others, at Tripos Receptor Research (Bude, UK) for the prediction of the success of compound synthesis.

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