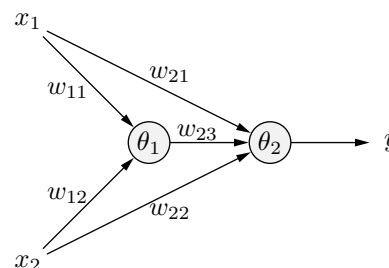


### Exercise Sheet 3

#### Exercise 11 Networks of Threshold Logic Units

Determine the parameters  $w_{ji}$  and  $\theta_j$  of the neural network of threshold logic units that is shown in the sketch on the right in such a way that it computes the Exclusive Or of the Boolean variables  $x_1$  and  $x_2$  (that is,  $y = x_1 \dot{\vee} x_2$  or  $y = x_1 \oplus x_2$ )!

(Hint: Start from a geometric interpretation of the computation in the input space of the neuron on the right and consider how you may use the output of the left neuron to arrange the points  $(x_1, x_2)$ , for which 1 or 0 should be produced, in such a way that they become separable by a plane.)



#### Exercise 12 Threshold Logic Units: Representation of Boolean Functions

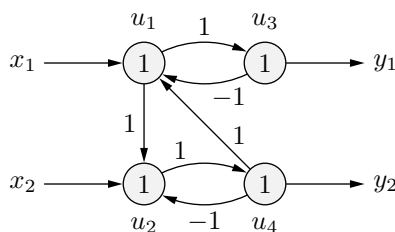
In the lecture we studied an algorithm with which, given an arbitrary Boolean function  $y = f(x_1, \dots, x_n)$ , a network of threshold logic units could be constructed that computed this function. This algorithm was based on representing the Boolean function in disjunctive normal form. Describe a dual algorithm that relies on representing the Boolean function in *conjunctive* normal form!

#### Exercise 13 Training Threshold Logic Units

Show how a threshold logic unit is trained (with the delta rule) to compute the Boolean function  $x_1 \rightarrow x_2$ ! (Preferably with the help of a table that has columns for the values of  $x_1$ ,  $x_2$ ,  $o = x_1 \rightarrow x_2$ ,  $\vec{x} \cdot \vec{w}$ ,  $y$ ,  $e$ ,  $\Delta\theta$ ,  $\Delta w_1$ ,  $\Delta w_2$ ,  $\theta$ ,  $w_1$  and  $w_2$ .) Start from the initial state  $\vec{w} = (0, 0, 0)$  of the (extended) weight vector and use 1 as the learning rate. Interpret the learning result geometrically!

#### Exercise 14 Update Order

Consider the following network of threshold logic units:



Show that it depends on the update order of the threshold logic units whether the network reaches a stable state if the the inputs  $x_1 = 0$  and  $x_2 = 1$  are presented!